

Global hydro-climatic
bioms identified via MTL

Global hydro-climatic bioms identified via multitask learning

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Abbreviations and clarifications:

- Biome = ecological region containing all its plants, animals and nonliving things
- Hydro-climate biome = regions of coherent vegetation-climate behaviour
- MTL - Multitask learning
- NDVI - Normalized Difference Vegetation Index
- ASO - Alternative structure optimization

Why identifying biomes?

- Gain a better understanding of complex interactions among different environmental variables.
- Used as a diagnostic of climate change by exploring their shifting boundaries
- Predict future climatic zone distributions using climate projections (tipping- & turning points)
- Unravel anomalous relationships between climate and vegetation dynamics

- Aim: data-driven approach that aims to quantify the response of vegetation to local climate variables in a supervised setting at a global scale

Data

Papagiannopoulou et al. (2017a)

- Combination of 21 datasets (mixutre of satellite and in situ observations)
- 1° lat - 1° long. resolution (13072 locations)
- 360 months - 30 years (1981 - 2010)
- Most important features (of 3209 climate variables):
 - land surface temperature
 - near-surface air temperature,
 - longwave-shortwave surface radiative fluxes
 - precipitation
 - snow water equivalent
 - soil moisture
- NDVI - Normalized Difference Vegetation Index
 - detrended & multiyear average for sesonal expectation

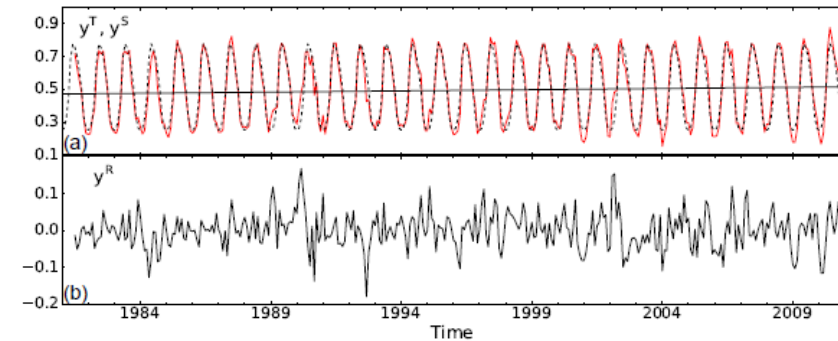
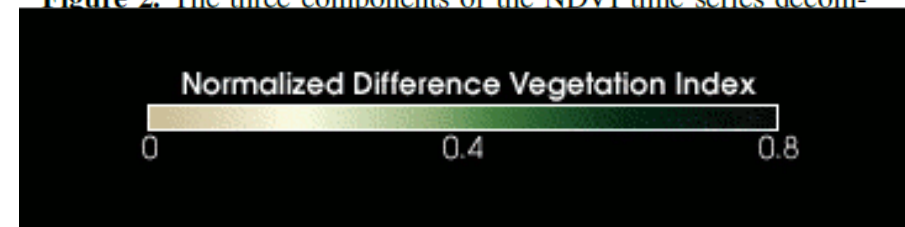
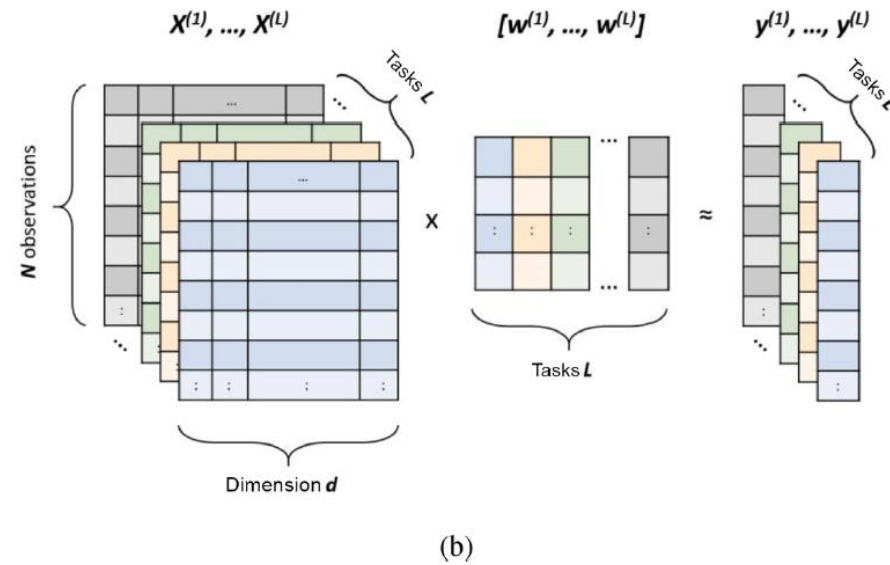
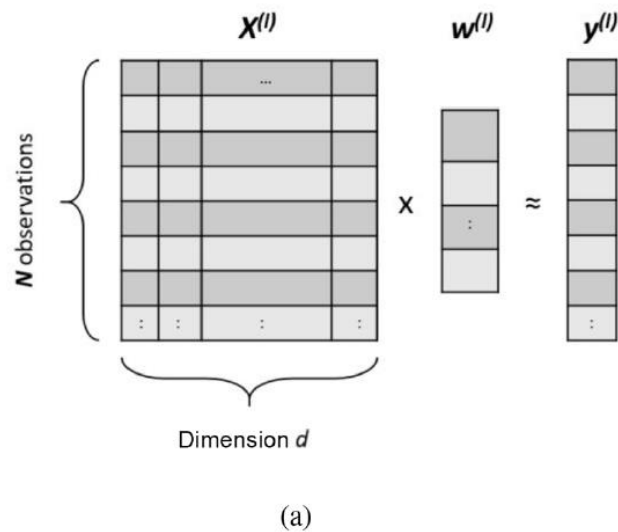


Figure 2. The three components of the NDVI time series decom-



Methods - Single task learning

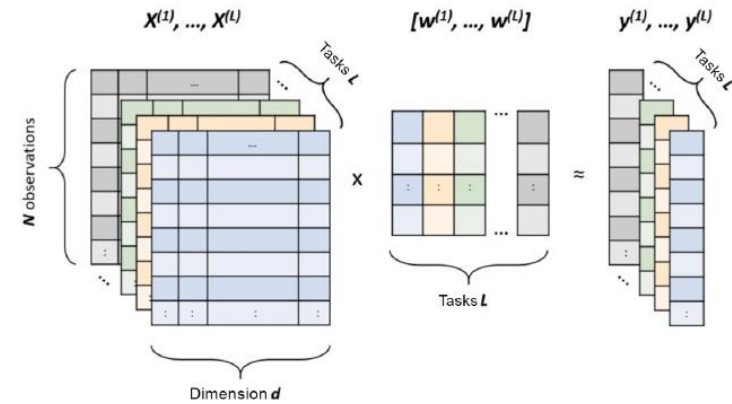
Pixel based approach:



Minimization problem:

$$\min_{\mathbf{w}^{(l)}} \sum_{i=1}^N \mathcal{L}(\mathbf{w}^{(l)} \mathbf{x}_i^{(l)}, y_i^{(l)}) + \lambda \|\mathbf{w}^{(l)}\|^2, \quad (\text{Ridge Regression})$$

Methods - Multitask learning



- Making use of spatial relationship between tasks
- Multitask minimization task

$$\min_{w^{(1)}, \dots, w^{(L)}} \sum_{l=1}^L \sum_{i=1}^N \mathcal{L}(w^{(l)} x_i^{(l)}, y_i^{(l)}) + \Omega(w^{(1)}, \dots, w^{(L)}),$$

- With Ω as a factor of relatedness between tasks

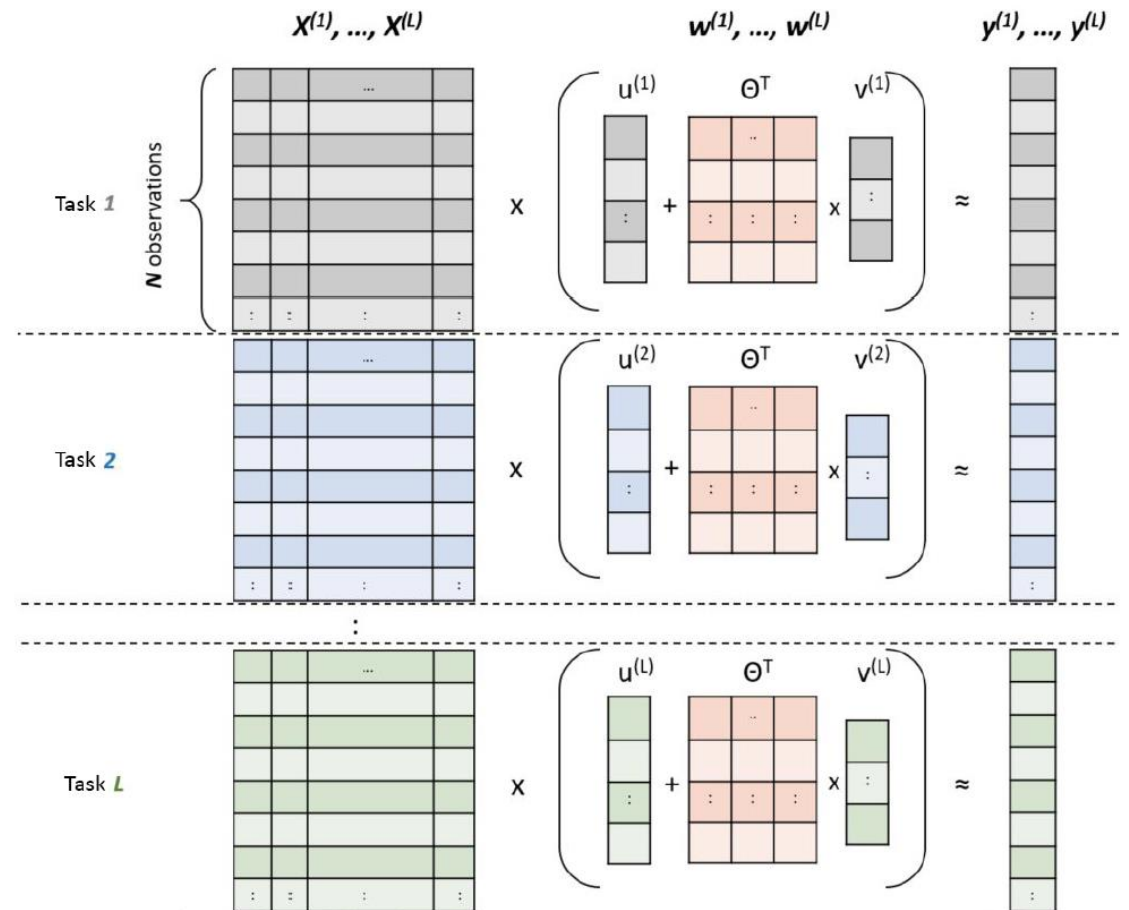
- SVD-based ASO for dimensionality reduction
- Compute low-dimensional feature map θ to look for similarities within the tasks
- Spectral clustering - hierarchical agglomerative clustering

Alternative Structure Optimization (ASO)

- Step 1: a model function for each individual task is learned
- Step 2: weight vector is decomposed by an SVD

$$f^{(l)}(x) = w^{(l)} x_i^{(l)} = u^{(l)} x_i^{(l)} + v^{(l)} \Theta x_i^{(l)},$$

- $w^{(l)} \in \mathbb{R}^d$ - weight vector of location l
- $u^{(l)} \in \mathbb{R}^d$ - high dim. weights representation
- $v^{(l)} \in \mathbb{R}^h$ - low dim. weights representation
- $\Theta^T \in \mathbb{R}^{d \times h}$ - low-dim. feature map



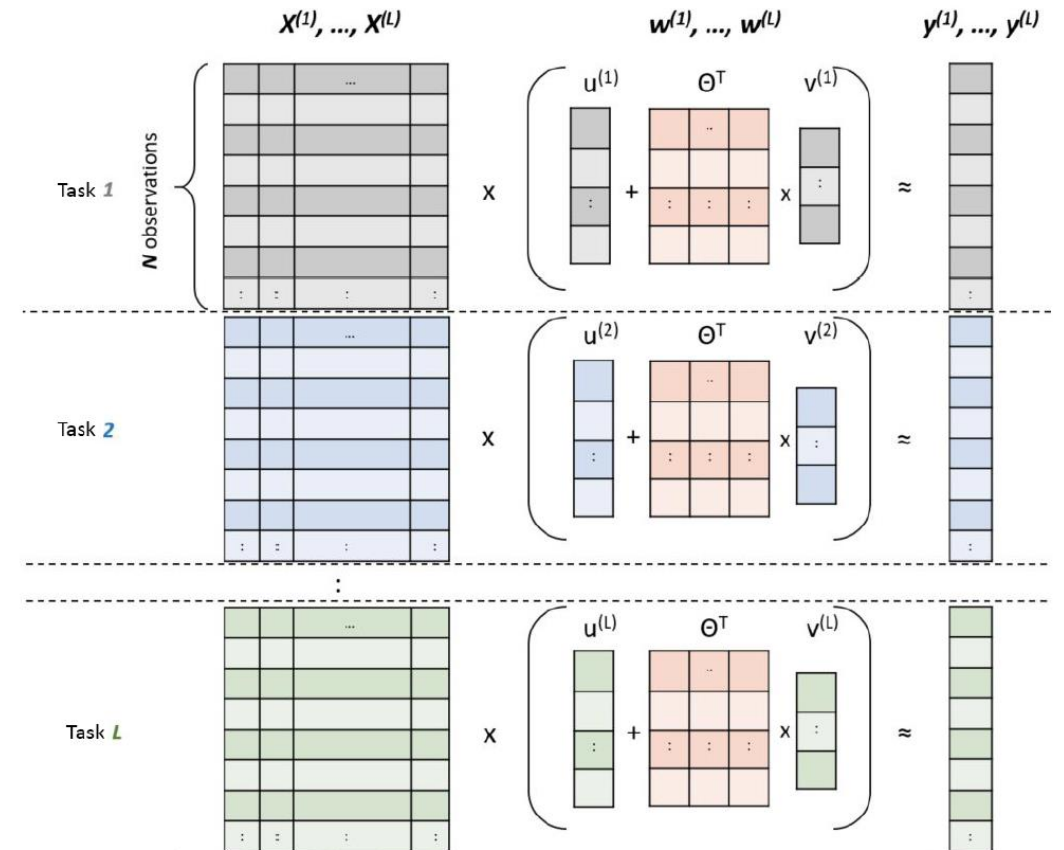
Alternative Structure Optimization (ASO)

- New minimization problem for ASO:

$$\min_{\{w^{(l)}, v^{(l)}\}, \Theta \Theta^T = \mathbf{I}} \sum_{l=1}^L \left(\sum_{i=1}^N \mathcal{L}(w^{(l)} x_i^{(l)}, y_i^{(l)}) + \lambda^{(l)} \|u^{(l)}\|_2^2 \right),$$

- With $\|u^{(l)}\|_2^2$ being a regularization term that controls task relatedness among all tasks
 - Penalizes difference between high- and low-dim. space

💡 $u^l = \omega^{(l)} - \Theta^T v^{(l)}$



Alternative Structure Optimization (ASO)

$$\text{💡 } u^l = \omega^{(l)} - \Theta^T v^{(l)}$$

Algorithm 1 SVD-ASO

Input: training data $D^{(l)} = \left\{ \left(\mathbf{x}_i^{(l)}, y_i^{(l)} \right) \right\}_{i=1, \dots, N}$,

where $l = 1, \dots, L$

Parameters: h and $\boldsymbol{\lambda} = \left\{ \lambda^{(1)}, \dots, \lambda^{(L)} \right\}$

Output: $\Theta \in \mathbb{R}^{h \times d}$ and $\mathbf{V} = \left[\mathbf{v}^{(1)}, \dots, \mathbf{v}^{(L)} \right]^T \in \mathbb{R}^{L \times h}$

Initialize: $\mathbf{w}^{(l)} = 0$, $l = 1, \dots, L$, and Θ to random

repeat

for $l = 1$ **to** L **do**

 with fixed Θ and $\mathbf{v}^{(l)} = \Theta \mathbf{w}^{(l)}$, solve the optimization problem of Eq. (3) for $\mathbf{u}^{(l)}$:

$$\operatorname{argmin}_{\mathbf{u}^{(l)}} \sum_{i=1}^N \mathcal{L} \left(\mathbf{u}^{(l)} \mathbf{x}_i^{(l)} + (\mathbf{v}^{(l)} \Theta) \mathbf{x}_i^{(l)}, y_i^{(l)} \right) + \lambda^{(l)} \|\mathbf{u}^{(l)}\|_2^2$$

$$\mathbf{w}^{(l)} = \mathbf{u}^{(l)} + \Theta^T \mathbf{v}^{(l)}$$

end for

 Apply an SVD decomposition on

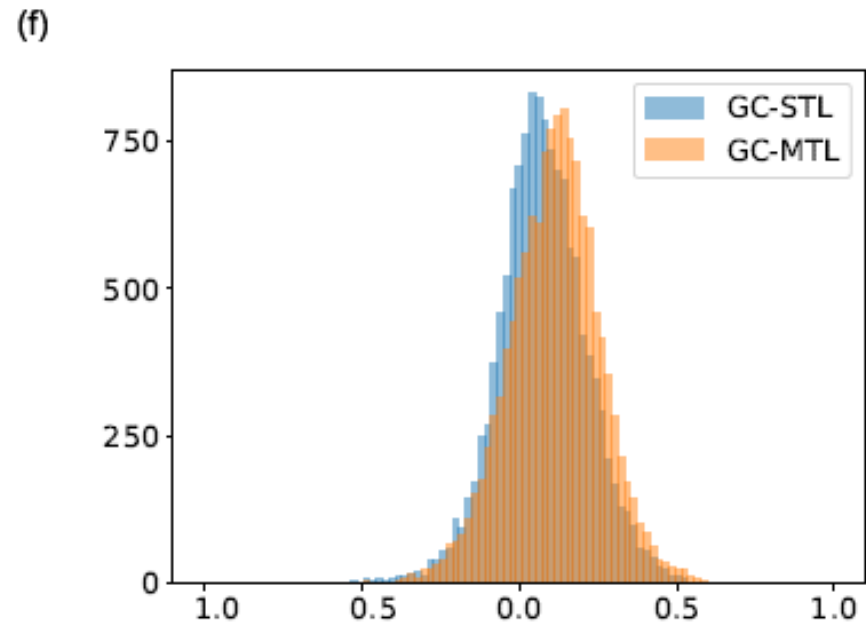
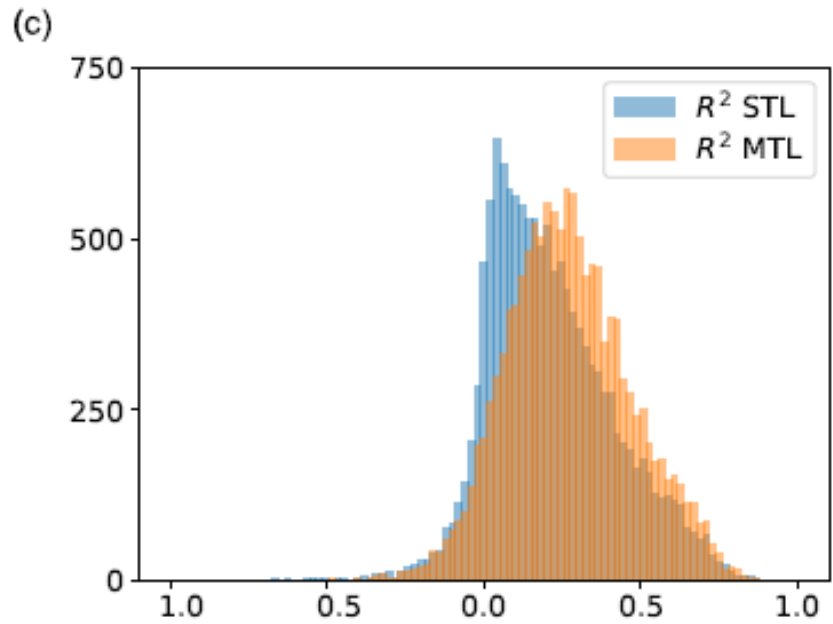
$$\mathbf{W} = \left[\sqrt{\lambda^{(1)}} \mathbf{w}^{(1)}, \dots, \sqrt{\lambda^{(L)}} \mathbf{w}^{(L)} \right]:$$

$\mathbf{W} = \mathbf{V}_1 \mathbf{D} \mathbf{V}_2^T$ (with diagonals of \mathbf{D} in descending order)

$\Theta = \mathbf{V}_1^T[:h, :]$ // update Θ to the first h rows of \mathbf{V}_1^T

until convergence

Performance of MTL compared to STL

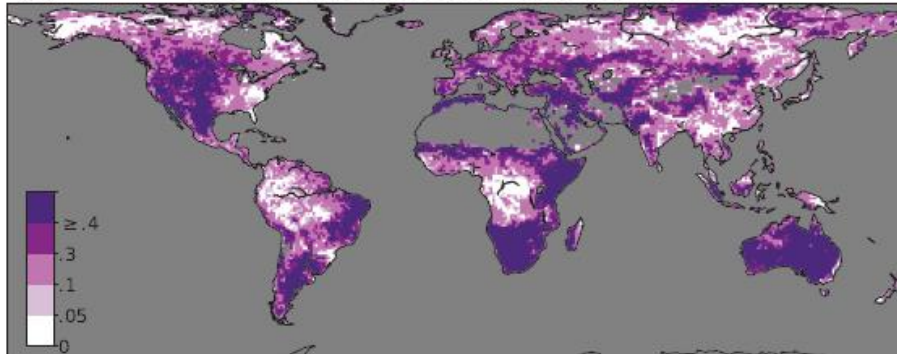


$$R^2(y, \hat{y}) = 1 - \frac{\text{RSS}}{\text{TSS}} = 1 - \frac{\sum_{i=P+1}^N (y_i - \hat{y}_i)^2}{\sum_{i=P+1}^N (y_i - \bar{y})^2},$$

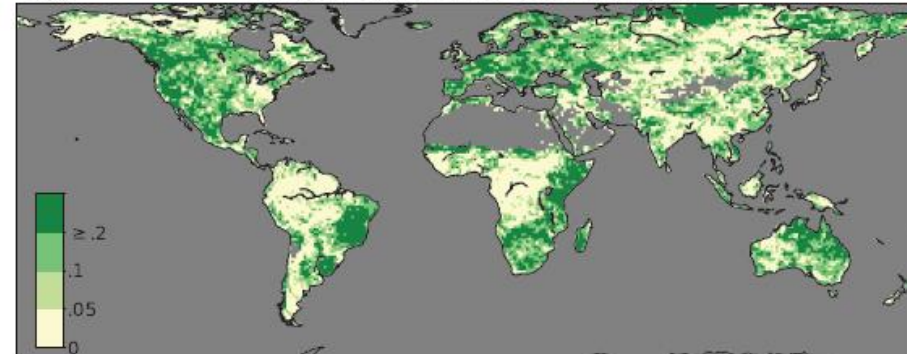
With \hat{y} : the predicted value
 \bar{y} : the mean of the timeseries

Comparison of Performance of MTL and STL

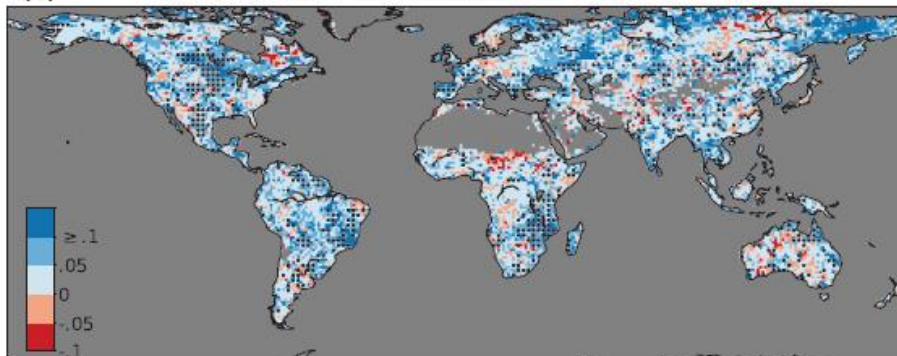
(a) Explained variance (R^2) of the MTL model



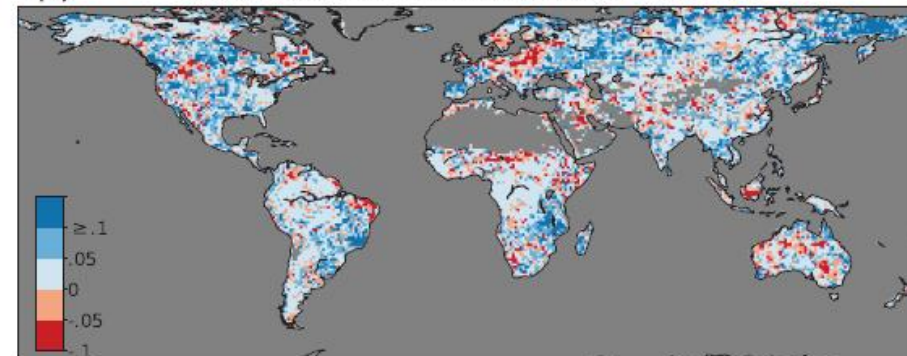
(d) Granger causality of the MTL model



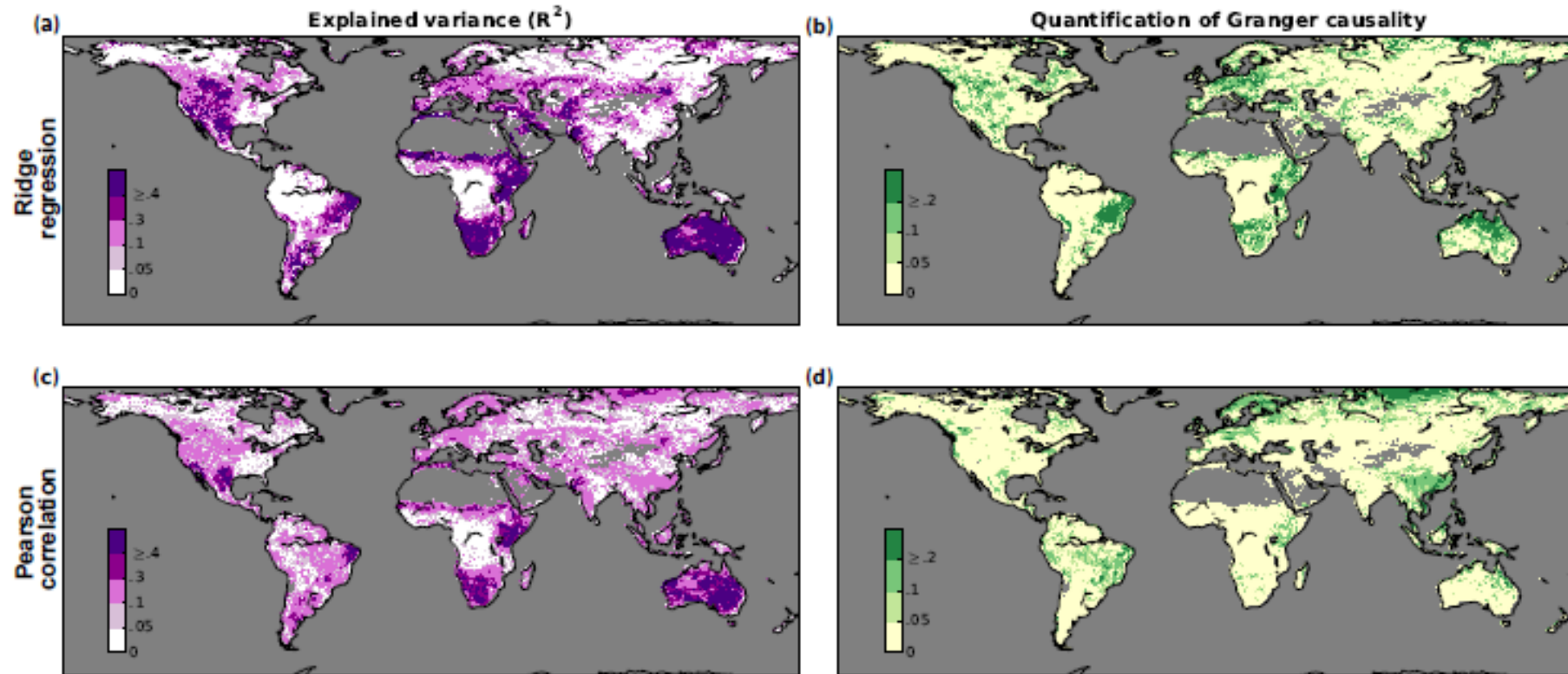
(b) Difference (R^2) between MTL and STL models



(e) Difference GC between MTL and STL models

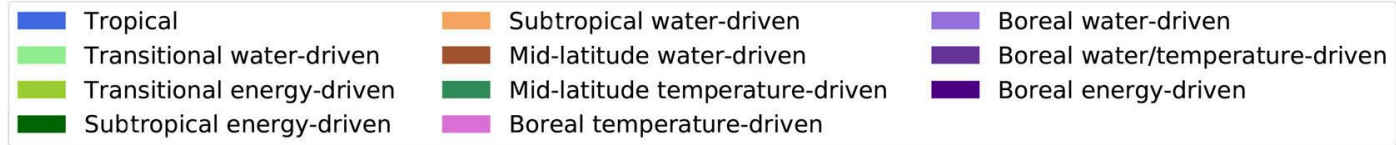
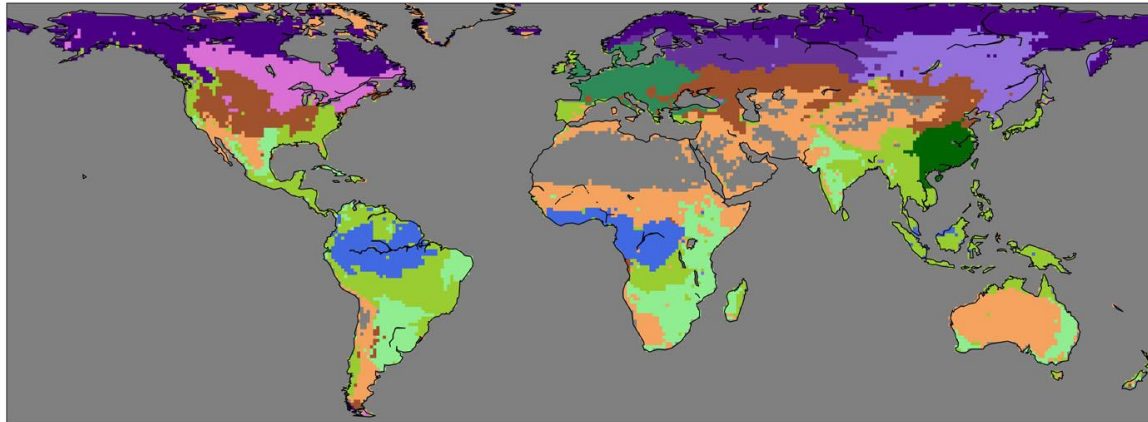


Variability and Granger Causality of the STL model

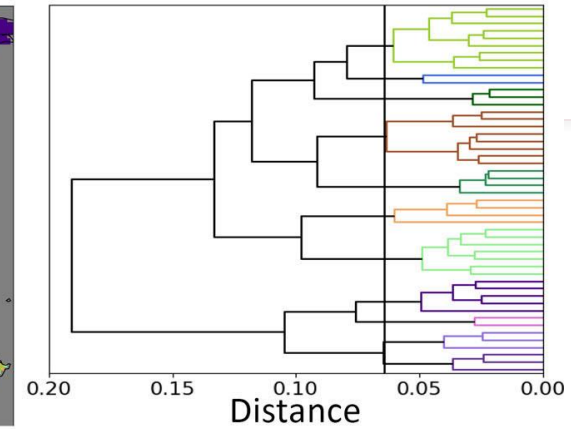


Classification of the MTL approach

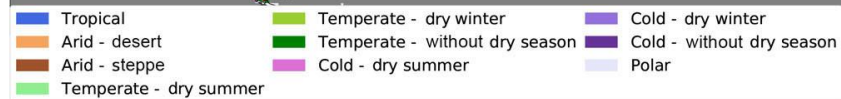
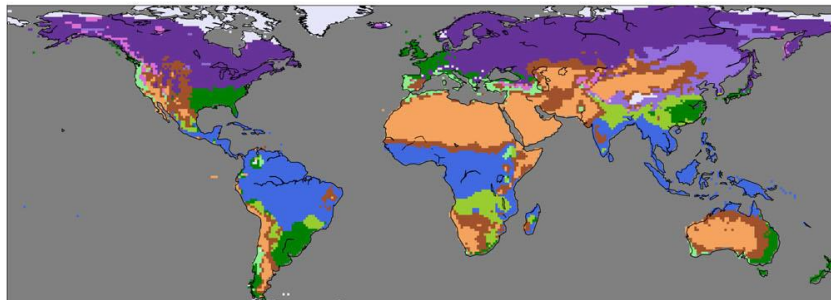
(a)



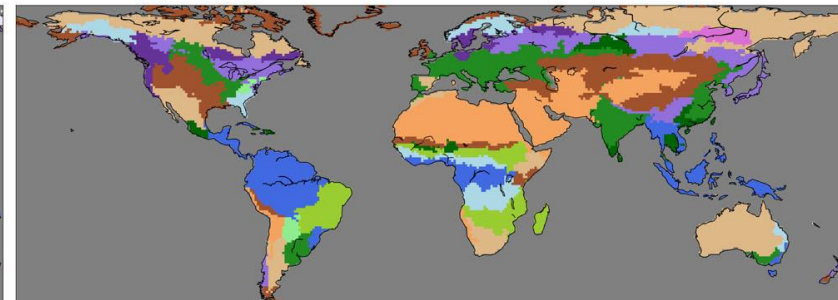
(b)



(c)



(d)



Scatter plots of MTL, Köppen-Geiger and IGBP

